

**Amendments to the Specification:**

Please replace the paragraph, beginning at page 5, line 30, with the following rewritten paragraph:

Drive assembly 12 typically comprises motor 88, gearbox 90 and drive shaft 92 on which drive magnet 22 is mounted, as are well known in the art. The particular configuration depicted in the drawings resembles a unit adapted to work with a Lightnin LIGHTNIN® MBI-410 submerged, bottom-mount, magnetic-drive mixer, but the drive assembly may comprise any components necessary for use with any type of mixer known in the art. Although depicted for use with a bottom-mount mixer, similar docking station arrangements may be devised for use with side-entry or top-entry mixers. Similarly, although a magnetic drive is a preferred quick connecting mechanism for coupling the drive to the mixer shaft, other connection mechanisms (preferably ones designed for quick connection and disconnection) known in the art may be used.

Please replace the paragraph, beginning at page 7, line 10, with the following rewritten paragraph:

Thus, linkage 34 translates the lateral motion of the tank toward the docking station into upward motion of drive magnet 22 into the drive magnet receiving hub 24 on tank 14. In the engaged configuration and in the transition from the disengaged to the engaged configurations, linkage 34 transmits a resultant downward force F on spring members 35, which is further transmitted to vertical support beam 86, which is essentially cantilevered off of mounting plate 82. To minimize the extent of the stress on the connection at mounting plate 82 that would otherwise be caused by the moment created by the resultant downward force on the cantilevered design, tank guide 18 is configured to support at least a portion of resultant downward force F. Force F is transmitted by bottom plate 38 to wheel 36 that is attached to forward bracket 44 46 and ultimately to undercarriage 20 of tank 14, thus distributing the forces accordingly.